



1           **A new tool for model assessment in the frequency domain -**  
2           **Spectral Taylor Diagram : application to a global ocean general**  
3           **circulation model with tides**

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13           **Abstract**

14           We introduce a new tool - the Spectral Taylor Diagram (STD) - for the comparison of time  
15           series in the frequency domain. The STD provides a novel way of displaying the  
16           squared-coherence, power, amplitude, phase, and root-mean-squared difference of discrete  
17           frequencies of two time-series. Each STD summarises these quantities in a single plot, for  
18           multiple targeted frequencies. The versatility of STDs is demonstrated through a series of  
19           sea-level comparisons between observations from tide gauges, and model results from a  
20           global eddy-permitting ocean general circulation model with explicit tidal forcing.

21           Keywords: Model evaluation; Spectral Taylor Diagrams; Ocean tides; global ocean modelling

22           Highlights:

- 23           • A new tool to evaluate tides is introduced: Spectral Taylor Diagram  
24           • Ocean General Circulation model with explicit tidal forcing.



## 25 1. Introduction

26 Ocean and climate modelling are widely used for research, forecasting, and climate  
27 projections. An important step in the application of an ocean or climate model is model  
28 assessment. This is commonly done by comparing model results to observations and  
29 reanalysis (Landerer and Glecker, 2014, Chiyuan Miao *et al* 2014), or to other models (Flato  
30 *et al.*, 2013). Such comparisons often involve single variable to multi-variables,  
31 multi-processes, and multi-phenomena employing methods of mathematical statistics for  
32 quantitative evaluations as well as parametric or nonparametric tests of significance.  
33 Traditional statistical comparisons in the time-domain typically include calculation of  
34 correlations, and comparison of standard deviations, means, and trends (e.g., Schiller and  
35 Brassington, 2011). Second order comparisons often compare some variant of empirical  
36 orthogonal functions (e.g., Erofeeva *et al.*, 2003). Comparisons in the frequency domain  
37 typically involve considerations of the cross-spectral density, squared-coherence, phase, and  
38 amplitude at a range of frequencies. In cases where a specific frequency band is targeted –  
39 to isolate a particular process, for example – analysis techniques such as wavelets, or  
40 complex demodulation are commonly employed (Flinchem and Jay, 2000). Each type of  
41 comparison has strengths and weaknesses. A challenge for any model assessment is the  
42 concise depiction of multiple statistical metrics for easy interpretation. Taylor Diagrams (TDs;  
43 Taylor, 2001) are now commonly used to concisely present multiple statistical properties from  
44 the comparison in the time-domain. In this paper, we introduce a tool that is analogous to  
45 TDs but for spectral comparisons – the Spectral Taylor Diagram (STD).

46 We demonstrate the versatility of STDs through a series of assessments of a global,  
47 eddy-permitting ocean general circulation model with explicit tidal forcing. To date, most  
48 global ocean models and climate models do not include explicit tidal forcing – with a few  
49 notable exceptions (Schiller 2004; Schiller and Fiedler 2007; Arbic *et al.*, 2012; Müller *et al.*,  
50 2012; and Ngdock *et al.* 2016) – largely because of the understanding that tidal energy is  
51 completely dissipated in shallow waters (Wunsch 2000). However, many observations of  
52 tides indicate that tides might be more important than previously thought. For example, Lee  
53 *et al.* (2006) shows that barotropic tidal energy in coastal regions is several orders of  
54 magnitude greater than the deep ocean. Moreover, Munk and Wunsch (1998) concluded that  
55 mixing driven primarily by dissipation of tidal energy could contribute to one half of the power  
56 required to return the deep waters to the surface.

57 The accuracy of ocean models, forced with tides, remains limited by uncertainties in a range  
58 of model parameters (Schiller 2004; Schiller and Fiedler 2007; and Ngdock *et al.* 2016),  
59 such as inaccurate bathymetry, bottom friction, model resolution, inaccurate estimation of



60 internal tides, and misrepresentation of the self-attraction and loading term (SAL). Another  
61 important source of barotropic errors in ocean modelling is introduced by an inaccurate  
62 estimation of phase information. In this study, we compare results from two model  
63 configurations with tides, to observations. We use version 5 of the Modular Ocean Model  
64 (MOM5) with its default tidal configuration (DFT) and with the addition of phase information  
65 (T8).

66 This paper is organised as follows. The STDs are described in section 2, the model is  
67 described in section 3, and applications of STDs are presented in section 4. We conclude  
68 and summarise our findings in section 5.

## 69 2. Spectral Taylor Diagrams – STDs

70 Taylor Diagrams (TDs; Taylor 2001) are often used to intercompare results from different  
71 models with observations (e.g., Oke et al. 2012). TDs (e.g., Figure 1) represent unbiased  
72 Root-Mean-Squared Error (RMSE; i.e., RMSE with the mean removed), the cross-correlation  
73 between observed and modelled estimates, and the standard deviation of the analysed  
74 time-series. Some presentations of TDs also include a metric of skill-score (e.g., Divikan et  
75 al. 2012). These diagrams nicely summarise a number of statistical comparisons in a single  
76 plot. TDs exploit the relationship between three statistical quantities that compose the law of  
77 cosines. The correlation coefficient ( $R$ ), the standard deviations of the test ( $\sigma_f$ ) and  
78 reference ( $\sigma_r$ ) fields, and the centered root-mean-square difference ( $E'$ ) between these two  
79 fields create a two-dimensional diagram through the following formula:

$$80 \quad E'^2 = \sigma_f^2 + \sigma_r^2 - 2 \sigma_f \sigma_r R \quad (1)$$

81 which resembles the law of cosines,

$$82 \quad c^2 = a^2 + b^2 - 2 a b \cos \varphi. \quad (2)$$

83 This geometric relationship is represented graphically in Figure 2.

84 In this paper, we introduce a new tool for inter-comparing different time-series against  
85 observations, based on a variant of TDs that we call STDs. Instead of calculating the  
86 correlation of an entire time-series with the observation, we select a frequency (or a band of  
87 frequencies) to be assessed. Here, a transformation is used to convert the time domain  
88 signal to the frequency domain. Furthermore, the choice of the three statistical quantities has  
89 to satisfy the law of cosines, such that the correlation is replaced by spectral coherence, and  
90 the standard deviation of the power replaces the time series standard deviation.



91 The squared-coherence is analogous to time domain measure of correlation, and is  
92 employed here since it also measures the strength of the linear relationship between two  
93 time series – ranging from 0 to 1 (the first quadrant of the diagram). Two time-series are  
94 considered highly coherent for a given frequency if the squared-coherency is close to 1 and  
95 the phase is close to 0 (Emery and Thomson, 2001). This is represented by

$$96 \quad \gamma_{12}^2(f_k) = |G_{12}(f_k)|^2 / G_{11}(f_k) G_{22}(f_k) , \quad (3)$$

97 where  $\gamma_{12}^2(f_k)$  is the squared-coherency,  $G_{11}(f_k)$  the one-sided Fourier spectrum of the first  
98 time-series for all frequencies ( $f_k, k = 0, 1, \dots, N - 1$ ),  $G_{22}(f_k)$  is the one-sided Fourier  
99 spectrum of the second time-series, and  $G_{12}(f_k)$  is the cross-spectrum between the first and  
100 the second time-series (Emery and Thomson, 2001).

101 The standard deviation of the power measures the amplitude of the signals while the  
102 centered RMS difference provides information about the centered pattern error, derived from  
103 the geometric relationship. The signals should combine higher coherence with enough  
104 energy to be considered co-oscillating.

105 The STD is like the TD, where the radial distances provide the standard deviations of the  
106 power, the azimuthal position gives the squared-coherence, and the concentric labeled lines  
107 indicate the centered RMS difference. The radial lines represent the cosine of the angle  
108 made with the abscissa thus consistent with Figure 2. The reference point (usually the  
109 observation data), marked with a black dot or star, is placed on the x-axis, whereas it's the  
110 one with the maximum coherence. The test data (e.g., the model's simulations) are  
111 assessed for the ability to represent the reference data.

112 Although the mathematical relationship applies to two quadrants of the STD, as in the TD,  
113 the STD is only meaningful in the first quadrant; since a negative coherence is not  
114 applicable. The best performance is given by the test with lowest centered RMS difference,  
115 higher coherence, and similar energy.

116 Figure 3 shows an example of an STD for artificial time series where there is a difference in  
117 the amplitude and phase of the “model” results that are being inter-compared with  
118 “observations”. The frequency in this case is fixed, but it is also possible to consider  
119 frequency bands. The tests are normalized by the reference standard deviation of the power.  
120 The amplitude changes are proportional to radial distances, except in the case where the  
121 test amplitude is a multiple of the reference amplitude, where the pattern described is  
122 horizontal and exactly positioned along the abscissa axis. An increase in amplitude by  
123 multiple values is expressed in the diagram as multiples of the standard deviation of the



124 normalized power. The coherence, in this case, is equal to 1, but horizontally shifted showing  
125 the amplification of the signal. For example, varying the amplitude by one third (solid blue  
126 line) or reducing by two thirds (dashed blue line), the coherence is reduced to 0.98 and 0.91,  
127 the centered RMS difference increases to 0.80 and 0.90, while the normalized standard  
128 deviation is extended to 1.77 and 0.11, respectively.

129 The coherence is highly dependent on the phase. Therefore, keeping the amplitude  
130 unchanged and only varying the phase values from one quarter (dashed red line) to plus one  
131 half (red line), the normalized standard deviation stays fixed, at 1, while the coherence is  
132 reduced from 0.76 to 0.27, and the centered RMS difference increases from 0.69 to 1.21.

133 The power spectrum shown in Figure 3D does not clearly demonstrate the contrast when  
134 varying the amplitude and phase of the time series. The STD displays both coherence and  
135 power, therefore, highlighting the co-oscillating frequencies overcoming the limited  
136 information contained in a power spectrum analysis. The need for better representing the  
137 degree of correspondence between simulated and observed fields for a given frequency (or  
138 frequency bands) is fulfilled by this novel tool inspired by relevant tide features.

### 139 3. Model Description

140 MOM5 (Griffies et al. 2012) is a hydrostatic (z-model), primitive equation model with free  
141 surface. The model configuration used here has a global grid of  $1/4^\circ \times 1/4^\circ$  horizontal  
142 resolution, comprised of 720X1400 grid points and with 50 vertical levels. The first vertical  
143 level is 10 m from the surface and vertical resolution of 10 m down to 220 m. Below this  
144 depth, the levels are discretized by 166 m to the bottom. This horizontal resolution is  
145 eddy-permitting and permits representation of barotropic tides. However, the model  
146 resolution is insufficient to resolve internal tides. Here, we focus on the explicit barotropic  
147 tidal forcing and its relevance for the contemporary HighResMIP for CMIP6 (Coupled Model  
148 Intercomparison Project 6) experiments that use global climate models with a similar  
149  $1/4^\circ \times 1/4^\circ$  resolution for ocean models (Haarsma et al., 2016).

150 The model topography is derived from ETOPO5<sup>1</sup>; the Boussinesq approximation is  
151 employed, and the vertical grid uses a  $z^*$  coordinate. The surface fields are extracted from  
152 the Coordinated Ocean-ice Reference Experiments (CORE1) using climatological forcing for  
153 temperature and salinity from Levitus and Boyer (1994). Surface heat fluxes, precipitation,  
154 wind stress, and river fluxes are from CORE1. Surface salinity is restored to monthly  
155 averaged climatology with a timescale of 60 days. The vertical viscosity and diffusivity are  
156 parameterized by the KPP scheme, updated from MOM4.0 to MOM4p1 to resolve the free

157 <sup>1</sup> <http://www.ngdc.noaa.gov/mgg/global/global.html>



158 surface undulation. Bryan-Lewis background diffusivity is turned off to prepare the model to  
159 use the barotropic dissipation from Lee et al. (2006) and baroclinic dissipation from Simmons  
160 et al. (2004) for future studies.

161 Three individual 20 years tidal simulations are run, which is sufficient to span the nodal tide  
162 period of 18.6 years. Each 20-year simulation is initialised from the final state of a 60-year  
163 spinup. We consider the spinup period to be sufficiently long for an evaluation of the upper  
164 ocean. The three experiments performed include: a control run without the tidal potential,  
165 hereafter referred to as CNTRL; a run equivalent to CNTRL, but with explicit tidal forcing  
166 using the eight principal lunisolar constituents (M2, S2, N2, K2, K1, O1, P1, Q1 without  
167 phase information, hereafter referred to as DFT (this is the default configuration of MOM5);  
168 and a run equivalent to DFT, but with phase information and amplitude adopted from OSU  
169 Tidal Inversion Software<sup>2</sup>, hereafter referred to as T8.

170 The sea elevation adjustment is virtually instantaneous assuming the ocean is always in  
171 equilibrium with tidal forces and disregarding the Darwin's correction when estimating the  
172 equilibrium tide height in the presence of continents (Marchuk and Kagan, 1989).  
173 Observations show that it is possible to simulate and predict the actual tide from equilibrium  
174 form considering that it has been delayed and distorted slightly by the process of generation  
175 and propagation (Schiller, 2004). The equilibrium tide in MOM5 is described considering the  
176 tide-generating potential with corrections due to both the earth tide self-attraction and  
177 loading (SAL). A scalar approximation to SAL is assumed to be equal to 0.948. The  
178 equilibrium of tides described as a sum of harmonics, mainly diurnal and semidiurnal  
179 constituents, is integrated into the momentum budget of the Boussinesq approximation  
180 added to the transport equation, as shown in details in Griffies et al. (2004).

181 The tidal amplitude and phase adopted in the T8 experiment are based on astronomical  
182 arguments used by OSU Tidal Prediction Software with initial condition dated 1st January  
183 1992 00:00 Greenwich time, shown in Table 1. No update is made to the astronomical  
184 argument of the partial tide that is known slightly time-dependent (Schwiderski, 1980).

#### 185 **4. Application of STDs**

186 As described in section 2, the traditional approach to model assessment is to compare  
187 individual statistics separately. An example of such an assessment is presented in Figure 4.  
188 This figure depicts the averaged amplitude of the semidiurnal (yellow) and diurnal (green)  
189 tides for 29 tide gauge stations around the world. This includes estimates at the end of the  
190 10<sup>th</sup> (coloured circle) and 20<sup>th</sup> (black circle) year of the DFT and T8 runs; and estimates from

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191 <sup>2</sup> <http://volkov.oce.orst.edu/tides/otis.html>



192 observations (grey circle). This comparison shows a mix of results. In some cases, the  
193 modelled and observed tidal amplitudes are similar (e.g., across the Pacific Ocean), while  
194 other cases there are large discrepancies between the modelled and observed tidal  
195 amplitudes (e.g., off North-Western Australia). These results are only one element of the  
196 comparisons needed to assess the model's reproduction of the tidal signals. Arguably, a  
197 better way of assessing the model's reproduction of the observed tidal signals is presented  
198 in Figure 5. The values in each STD are normalized by the reference standard deviation of  
199 power, enabling the inter-comparison of the change in model performance over different  
200 periods of the simulation.

201 In the Atlantic, the T8 experiment shows a noticeable improvement for diurnal constituents  
202 (Fig.5A) at the selected Ilha Fiscal tide gauge, which is not evident in Figure 4. The  
203 coherence increased from 0.59 to 0.72 and the centered RMS error reduced from 1.03 to  
204 0.95. However, T8 overestimates the energy content from 1.22 to 1.36. DFT has a better  
205 response for semidiurnal constituents (coherence increases from 0.66 to 0.73) while T8  
206 keeps almost unchanged. At the Gan tide gauge station it is also difficult to differentiate  
207 between the experiments in Figure 4, but it is well stated in Figure 5B that T8 improves both  
208 semidiurnal and diurnal constituents. For both experiments, all tidal constituents are  
209 underestimated at the Gan tide gauge station. In the Pacific, at Townsville tide gauge station,  
210 T8 has improved the coherence for semidiurnal from 0.56 to 0.68 and for diurnal constituents  
211 from 0.54 to 0.72. However, DFT has a better estimate for diurnal constituents, reducing the  
212 centered RMS error from 0.82 to 0.65, enhancing the coherence from 0.59 to 0.76, and  
213 increased power from 0.69 to 0.83 as shown in Figure 5C. The semidiurnal constituents  
214 started with higher coherence in DFT (Figure 5C) in agreement with Figure 4, but decreased  
215 throughout the run. The higher coherence shown by the semidiurnal constituents for the vast  
216 majority of tide gauges is due to a severe underestimation of power and therefore amplitude  
217 in the model's simulations.

218 A comprehensive assessment of the model for all stations focusing on one frequency and a  
219 single (Figure 6) or multiple bands of frequencies (Figure 7) is only possible by using STD.  
220 A selection of the 17 tidal stations with significant data for evaluate long term frequencies is  
221 done for Figure 6 and 7. It's possible to certify that the model superestimates semidiurnal  
222 and diurnal bands in the Bering Sea (tide station number 12) while underestimates long term  
223 and semidiurnal bands for most of tide stations. As expected, M2 is also underestimated in  
224 the model expect for region close to north-eastern coast of Queensland (tide station number  
225 6).



226 Separated in basins style, Figure 7 shows that is possible to evaluate multiple bands in  
227 multiple regions. The model has better response to diurnal band, than in other frequencies.  
228 In the Atlantic, the better response was shown close to Palmeira, Halifax and Ilha Fiscal tide  
229 stations, as shown in Figure 7. The best response of diurnal band it placed in the Indian  
230 Ocean, where the best fit is shown in Gan tide station (shown in APPENDIX A). Australia  
231 diurnal band is well represented by the model in both Indian and Pacific Oceans. The M2,  
232 semidiurnal and long-term bands are underestimated in the model except for regions close  
233 to Townsville (better response for M2) and Fremantle (overestimated semidiurnal band)  
234 (shown in APPENDIX A).

## 235 **5. Conclusions and Further applications**

236 A new tool designed to help in the assessment and inter-comparison of model results in the  
237 frequency domain is presented. The STD arguably provide a better summary of each  
238 comparison – better highlighting the positive and negative aspects of each comparison.  
239 STDs may benefit other studies that seek to assess models – or inter-compare models – for  
240 specific frequencies, or for specific frequency bands, that might correspond to a particular  
241 process of interest. For the examples used to showcase this new analysis tool in this study,  
242 we showed a series of comparisons between a global model with explicit tidal forcing.  
243 In contrast to Taylor Diagram, the spectral version enables a multiple band of frequencies  
244 preview without using filtering techniques. Multi regions comparison it's also possible using a  
245 normalized standard deviation of power strategy, that can be also useful to track model's  
246 skills over different periods of the simulation. The versatility of STD is based on detection of  
247 anomalous patterns in a phenomena analysis.

248 Although the STD has been designed for tidal analysis purpose, it is a powerful tool to detect  
249 co-oscillating patterns in multi scale analysis, and may provide a guidance in devising skill  
250 scores for inter-compare models.

## 251 **Code and data availability**

252 Spectral Taylor Diagram is an open source script available at <https://github.com/mabelcalim>,  
253 as well as the figures plots created with IPython Notebook. The harmonic analysis based on  
254 pytides (available in <https://github.com/sam-cox/pytides>), an open source script in python  
255 made by Sam Cox, was parallelized in the Brazilian Supercomputer Tupã.





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338 *Table 1: Global constants of tidal frequency, amplitude, and phase applied for experiments*  
 339 *DFT and T8. Love numbers are frequency dependent and generally close to 0.7.*

Tidal Mode		frequency (Hz)	Love numbers	DFT	T8	
				amplitude (m)	amplitude (m)	Phase (rad)
semidiurnal						
M2	principal lunar	$1.40519 \cdot 10^4$	0.693	0.242334	0.244102	1.731557546
S2	principal solar	$1.45444 \cdot 10^4$	0.693	0.112743	0.113568	0.000000000
N2	elliptical lunar	$1.37880 \cdot 10^4$	0.693	0.046397	0.046735	6.050721243
K2	declination luni-solar	$1.45842 \cdot 10^4$	0.693	0.030684	0.030879	3.487600001
diurnal						
K1	declination luni-solar	$0.72921 \cdot 10^4$	1.0+0.256-0.520	0.141565	0.142435	0.173003674
O1	principal lunar	$0.67598 \cdot 10^4$	1.0+0.298-0.603	0.100661	0.101270	1.558553872
P1	principal solar	$0.72523 \cdot 10^4$	1.0+0.287-0.603	0.046848	0.047129	6.110181633
Q1	elliptical lunar	$0.64959 \cdot 10^4$	1.0+0.298-0.603	0.019273	0.019387	5.877717569

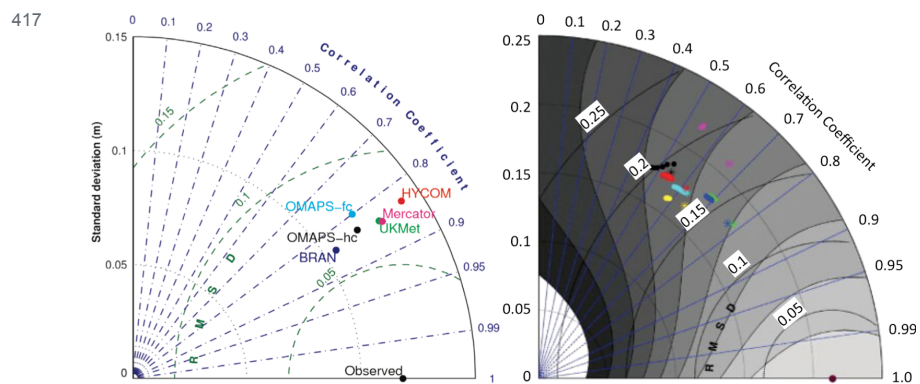
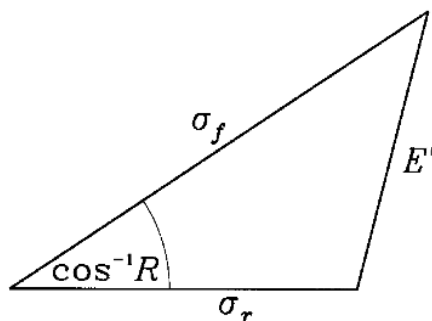


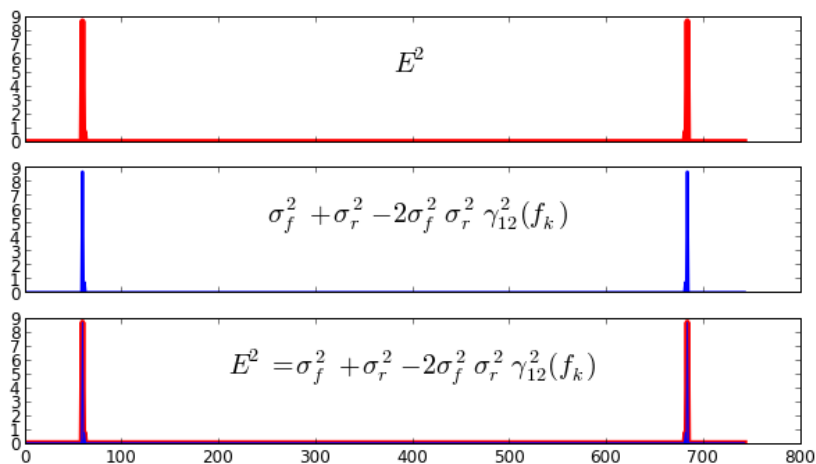
Figure 1: Example of a standard Taylor Diagram (left; adapted from Oke et al. 2012); and a Taylor Diagram with a skill-score (right; adapted from Divakaran et al. 2012).



420



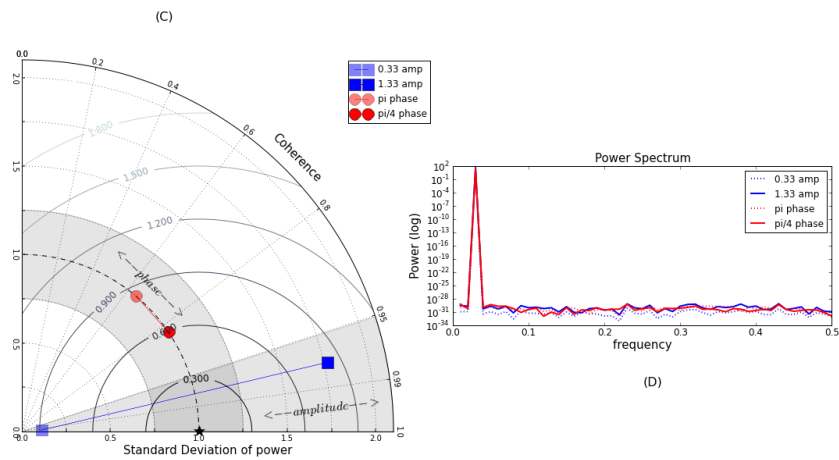
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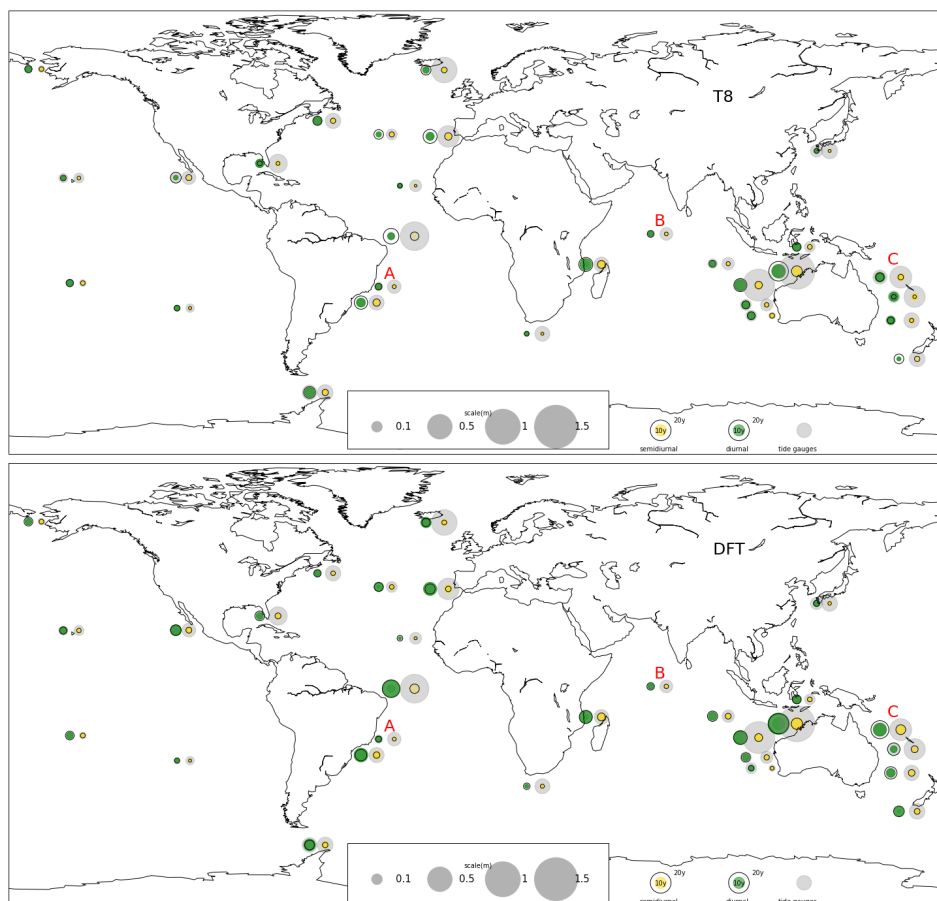
422 Figure 2: Upper panel: Geometric relationship between correlation coefficient ( $R$ ), the  
 423 standard deviations of the test ( $\sigma_f$ ) and the reference ( $\sigma_r$ ) fields, and the centered  
 424 root-mean-square difference ( $E'$ ) in a TD (Taylor, 2001). Lower panel: artificial series  
 425 demonstrating the validity of this relationship, root-mean-square difference (in red) equals to  
 426 second term of the equation (in blue).



427

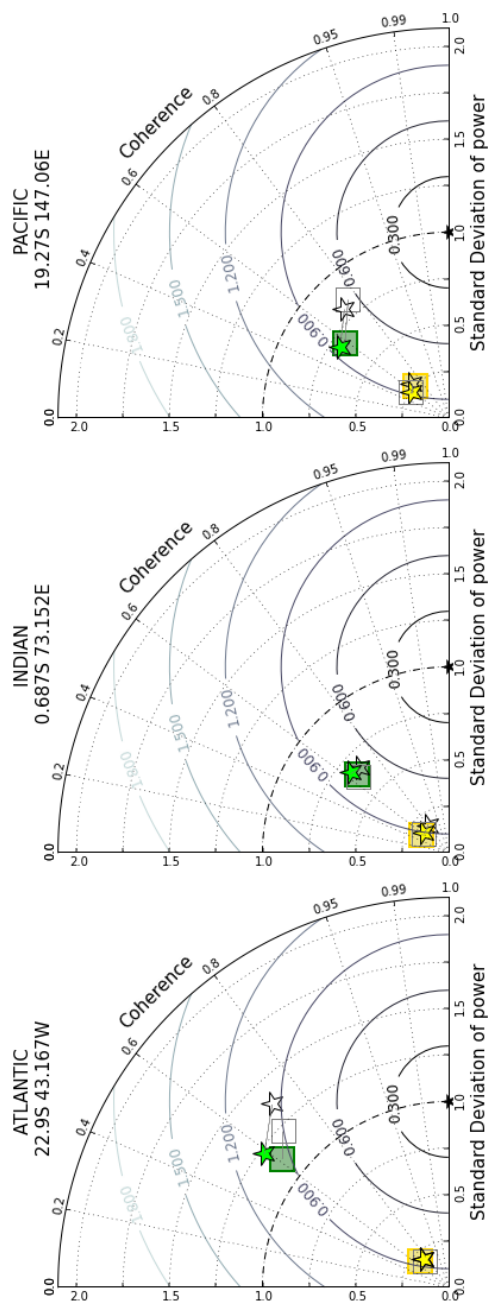


428 *Figure 3: Spectral Taylor Diagram for displaying patterns in frequency domain shown in (C).*  
429 *The relationship between three statistical quantities: coherence, standard deviation of power,*  
430 *and centered RMS difference are shown. The reference point is marked with a black star,*  
431 *plotted along the abscissa, and all the tests are normalized by the reference standard*  
432 *deviation of power. Artificial series created for test changes in: (A) amplitude and (B) phase.*  
433 *The frequency is fixed for all time series, where obs is the reference, amplitude is changing*  
434 *from 0.33 to 1.33, and the phase is changing from 180° to 45°. The standard deviations are*  
435 *proportional to radial distances, the azimuthal position gives the coherence while the*  
436 *concentric labeled lines indicate the centered RMS difference. The Spectral Taylor Diagram*  
437 *better expresses both the changes in amplitude and phase not captured by the power*  
438 *spectrum analysis, shown in (D).*



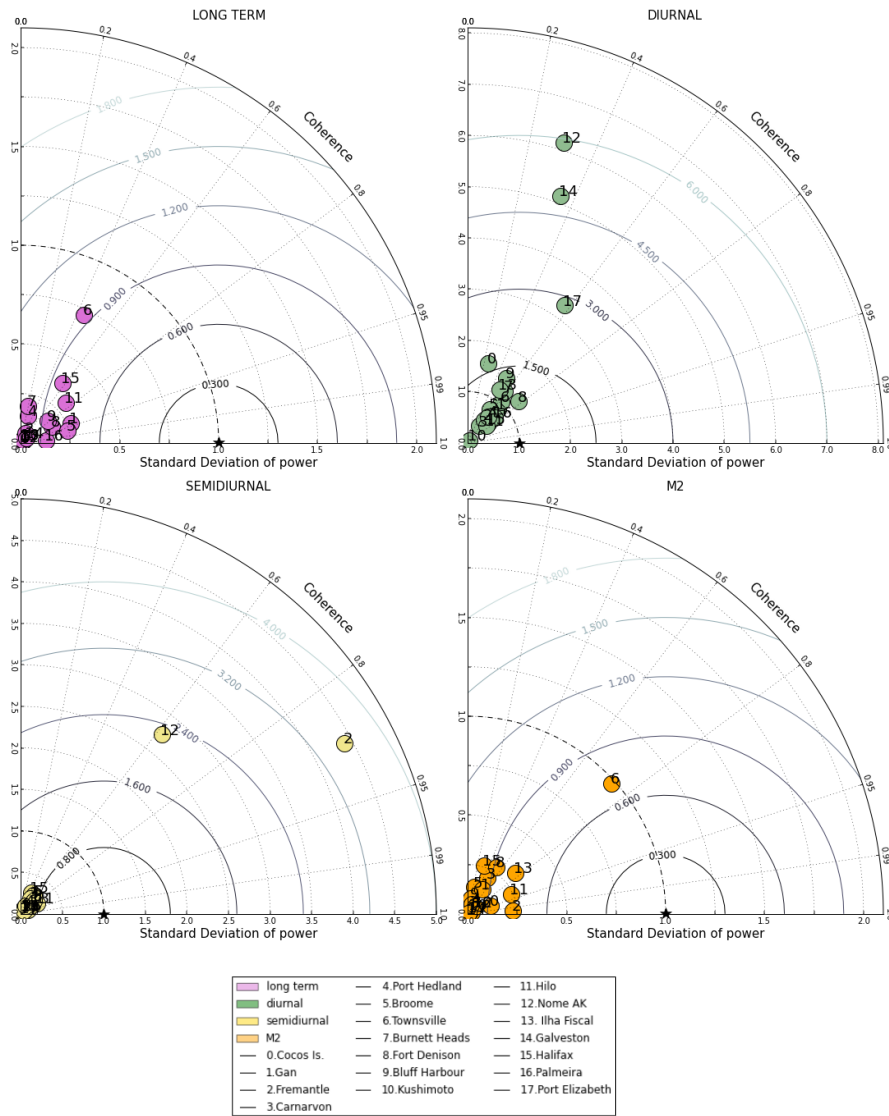
439 *Figure 4: Amplitudes of semidiurnal (yellow) and diurnal (green) averaged tidal constituents*  
440 *estimated after 10th and 20th year of simulation for T8 (top panel) and DFT (lower panel)*  
441 *compared to tidal gauges (grey) from GLOSS.*



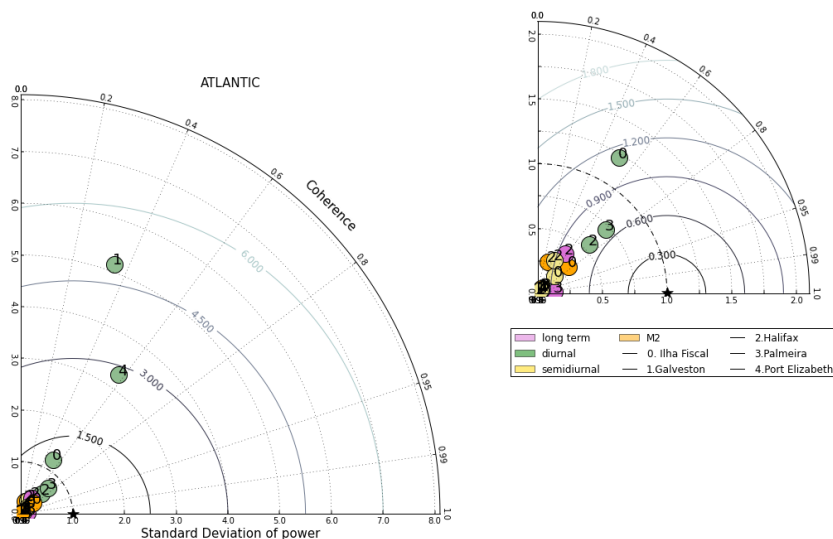




442 *Figure 5: STDs comparing sea-level from T8 and DFT with tidal gauge observations during*  
443 *DJF for an example in the A) Atlantic Ocean (Ilha Fiscal); B) Indian Ocean (Gan); and C)*  
444 *Pacific Ocean (Townsville) – showing the semidiurnal (yellow) and diurnal (green) averaged*  
445 *constituents for DFT (squares) and T8 (stars) at the end of the 10th (filled markers) and 20th*  
446 *(unfilled markers) year of each simulation. The 10th year is connected with 20th year of*  
447 *simulation by a line showing the evolution of the skill of the model's in relation of tide gauge*  
448 *data. The standard deviations of power have been normalized by the observed standard*  
449 *deviation of power. The reference (black star) is also divided into two time periods: 10 years*  
450 *and 20 years after initial condition of 01/01/1992.*



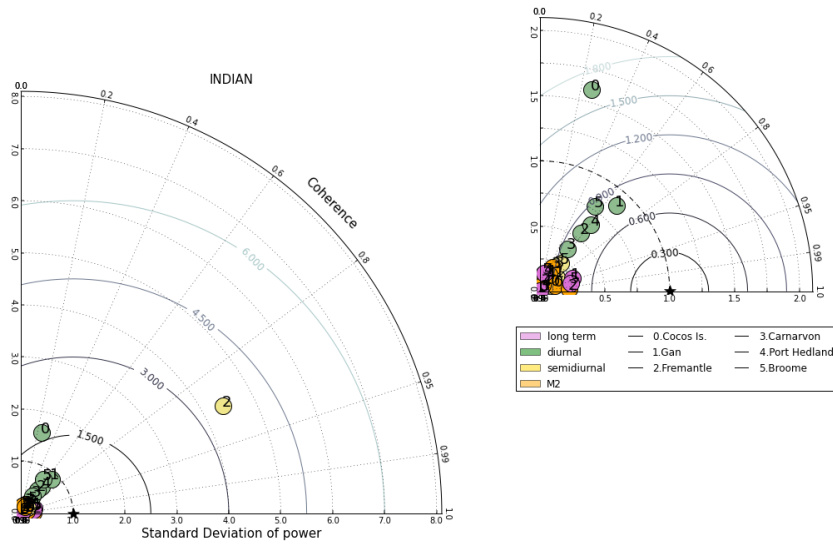
451 *Figure 6 - STDs overall tide gauges stations with significant data (17) separated by*  
 452 *frequencies. Upper left: long-term band; Upper right: diurnal band; Lower left: semidiurnal*  
 453 *band; and Lower right: M2 frequency. The model does a better job close to Townsville tide*  
 454 *station for M2 frequency, diurnal and long-term bands.*



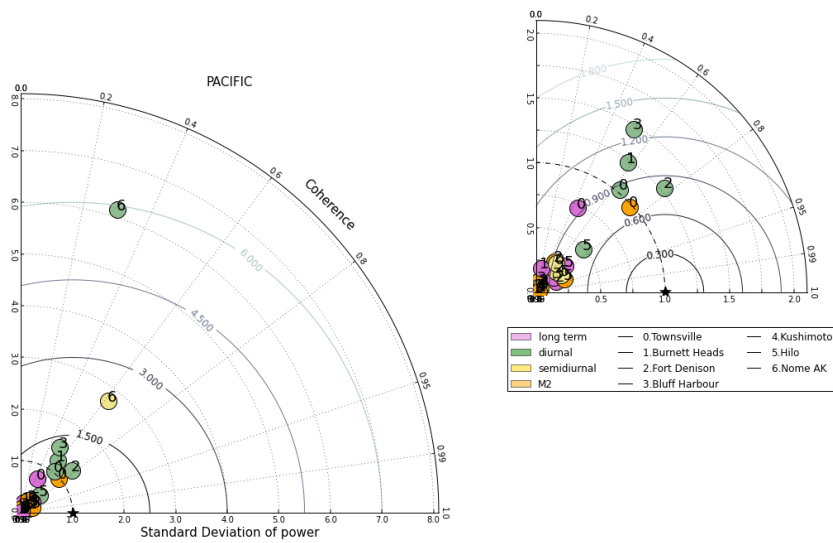
455 *Figure 7. STD overall tide gauges stations with significant data (5) in Atlantic Ocean.*



456 **APPENDIX A**



457 *Figure A1. STD overall tide gauges stations with significant data (6) in Indian Ocean.*



458 *Figure A2. STD overall tide gauges stations with significant data (5) in Pacific Ocean.*